

# What is a superrigid subgroup?

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## Abstract

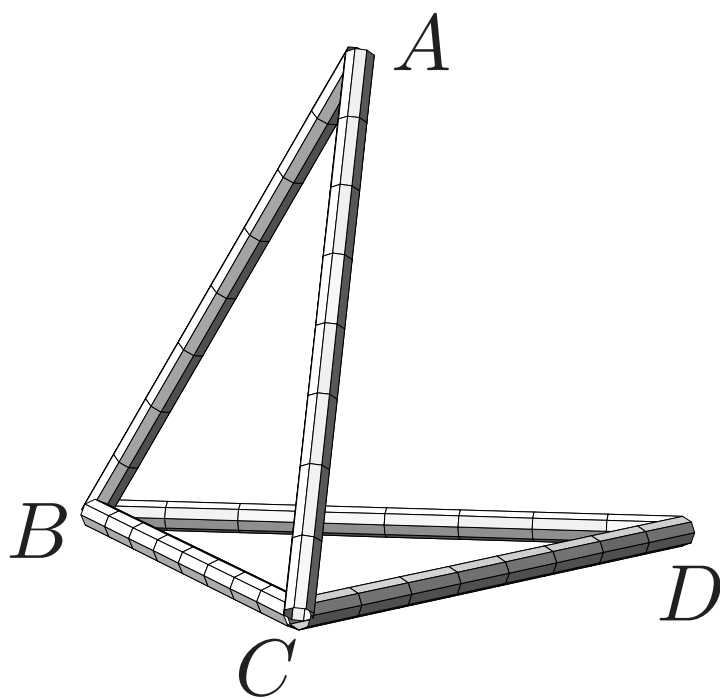
It is not difficult to see that every group homomorphism from  $\mathbf{Z}^k$  to  $\mathbf{R}^n$  extends to a homomorphism from  $\mathbf{R}^k$  to  $\mathbf{R}^n$ . (Essentially, this is the fact that a linear transformation can be defined to have any desired action on a basis.) We will see other examples of discrete subgroups  $\Gamma$  of connected groups  $G$ , such that the homomorphisms defined on  $\Gamma$  can (“almost”) be extended to homomorphisms defined on all of  $G$ .

What is a superrigid subgroup?

- (1. Combinatorial superrigidity)
2. Group-theoretic superrigidity
- (3. The analogy)
4. Superrigid subgroups

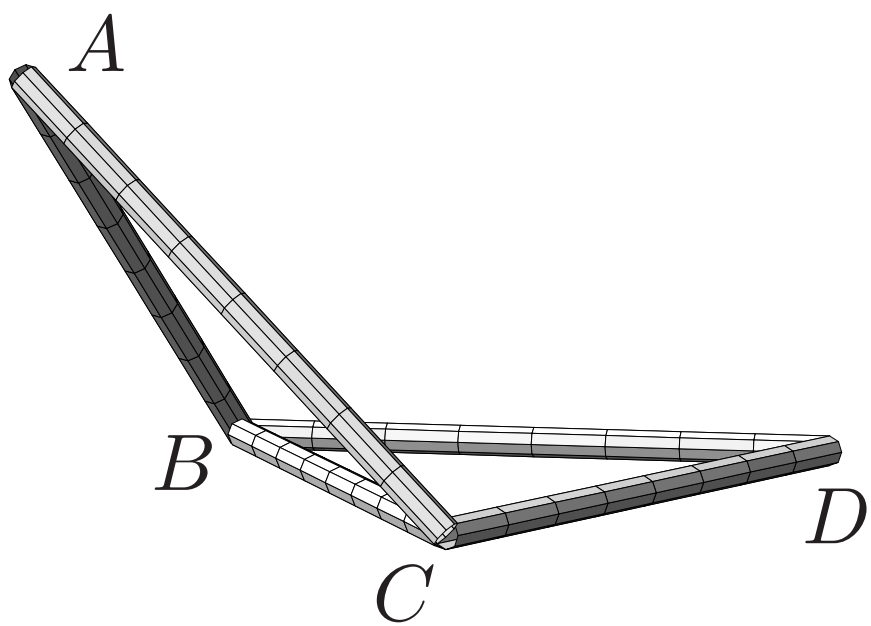
# (1. Combinatorial superrigidity)

*Eg.* Two joined triangles

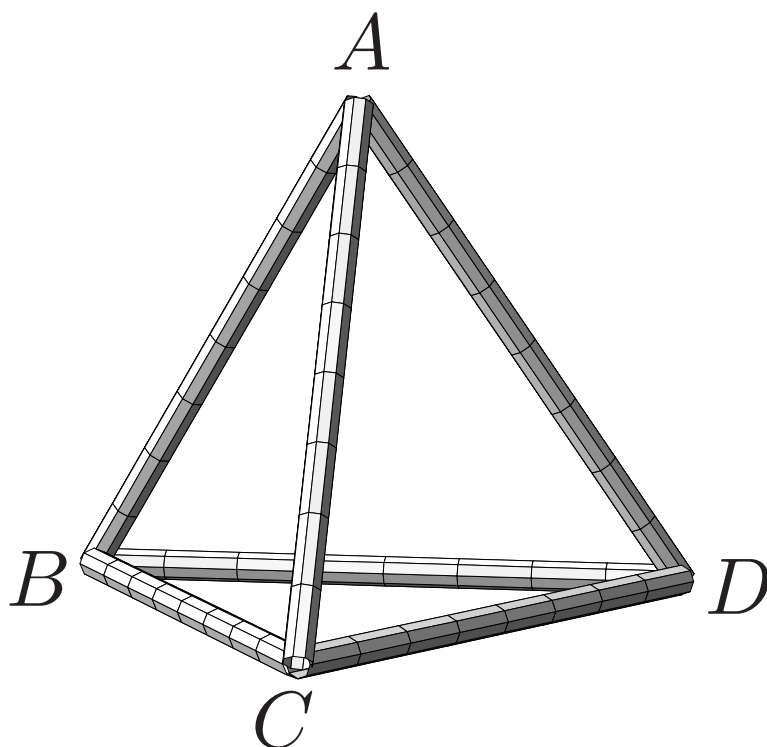


This is not rigid.

I.e., it can be deformed (a “hinge”).



*Eg.* Tetrahedron



$A$ — $B$

$A$ — $C$

$A$ — $D$

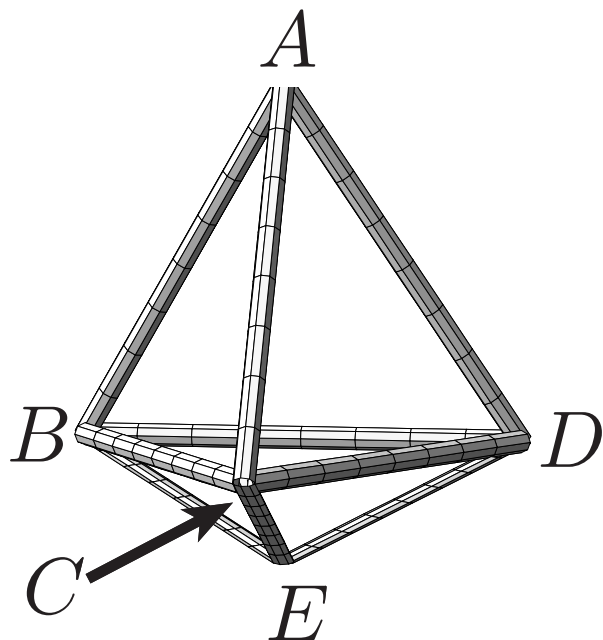
$B$ — $C$

$B$ — $D$

$C$ — $D$

This is **rigid** (cannot be deformed).

*Eg.* Add a small tetrahedron



$A$ — $B$

$A$ — $C$

$A$ — $D$

$B$ — $C$

$B$ — $D$

$C$ — $D$

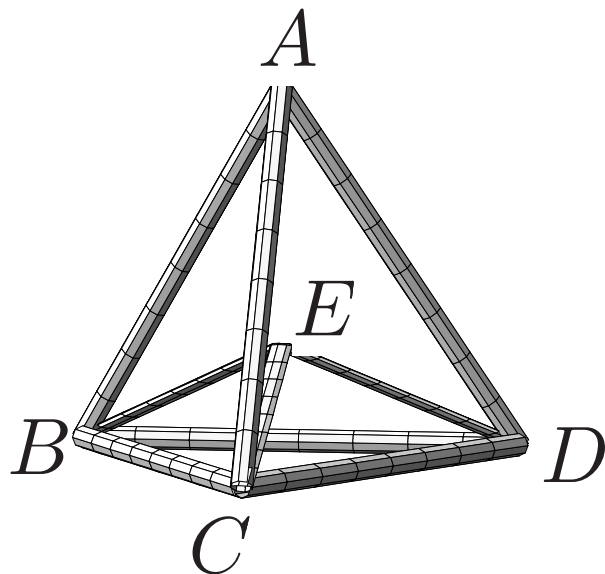
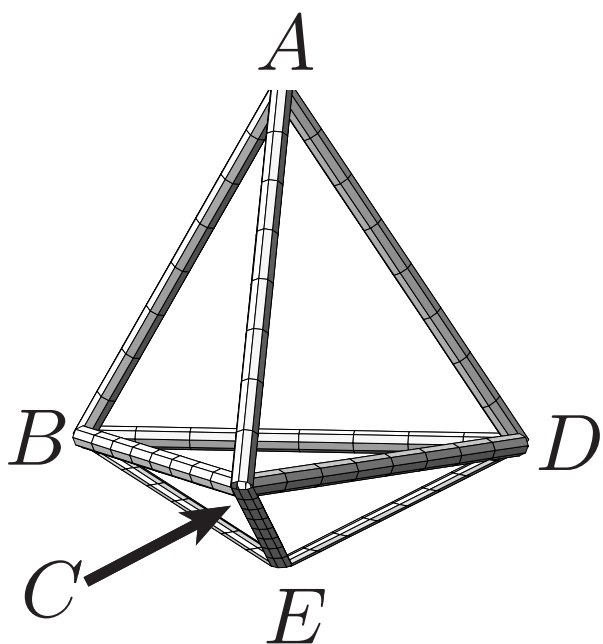
$B$ — $E$

$C$ — $E$

$D$ — $E$

This is rigid.

However, it is not **superrigid**:  
 if it is taken apart,  
 it can be reassembled incorrectly.



$A$ — $B$

$A$ — $C$

$A$ — $D$

$B$ — $C$

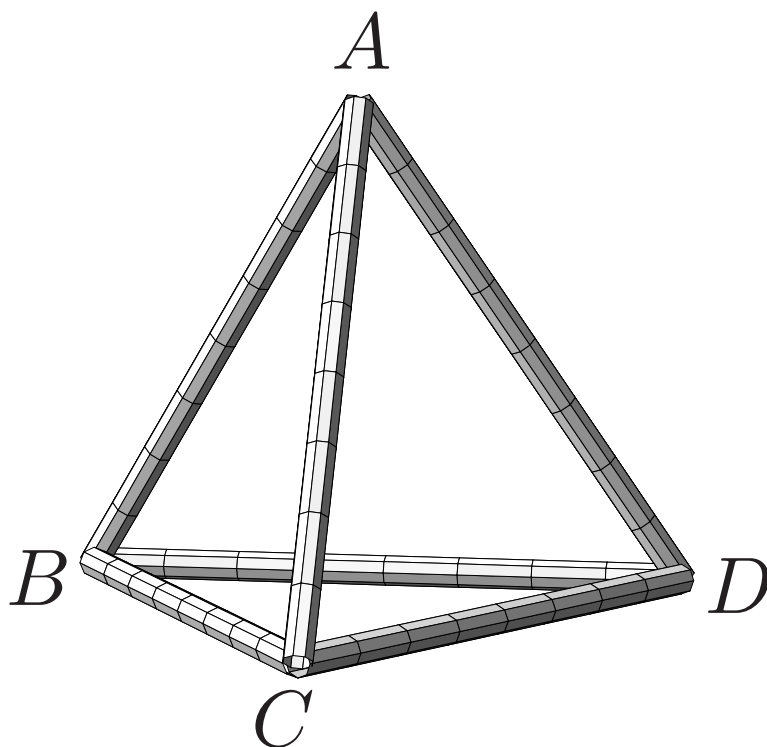
$B$ — $D$

$C$ — $D$

$B$ — $E$

$C$ — $E$

$D$ — $E$


 $A \text{---} B$ 
 $A \text{---} C$ 
 $A \text{---} D$ 
 $B \text{---} C$ 
 $B \text{---} D$ 
 $C \text{---} D$ 

A tetrahedron *is* superrigid: the combinatorial description determines the geometric structure.

### **Combinatorial superrigidity:**

Make a copy of the object,

according to the combinatorial rules.

The copy is the exact same shape as the original.

*This talk:* analogue in group theory



## 2. Group-theoretic superrigidity

Group homomorphism  $\phi: \mathbb{Z} \rightarrow \mathbb{R}^d$

$$\text{(i.e., } \phi(m + n) = \phi(m) + \phi(n)\text{)}$$

$\Rightarrow \phi$  extends to a homomorphism  $\hat{\phi}: \mathbb{R} \rightarrow \mathbb{R}^d$ .

Namely, define  $\hat{\phi}(x) = x \cdot \phi(1)$ .

*Check:*

- $\hat{\phi}(n) = \phi(n)$
- $\hat{\phi}(x + y) = \hat{\phi}(x) + \hat{\phi}(y)$
- $\hat{\phi}$  is continuous

(only allow continuous homomorphisms)

Group homomorphism  $\phi: \mathbb{Z}^k \rightarrow \mathbb{R}^d$

$\Rightarrow \phi$  extends to a homomorphism  $\hat{\phi}: \mathbb{R}^k \rightarrow \mathbb{R}^d$ .

*Proof.* Use standard basis  $\{e_1, \dots, e_k\}$  of  $\mathbb{R}^k$ .

“A linear transformation can have any desired effect on a basis.”

Linear transformation

$\Rightarrow$  homomorphism of additive groups

**Group Representation Theory:**

study homomorphisms into *Matrix Groups*.

$GL_d(\mathbb{C}) = d \times d$  matrices over  $\mathbb{C}$

with nonzero determinant

This is a group under multiplication.

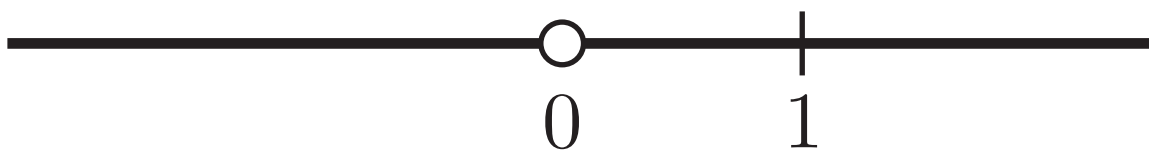
$$\mathbb{R}^d \cong \begin{pmatrix} 1 & 0 & 0 & \mathbb{R} \\ 0 & 1 & 0 & \mathbb{R} \\ 0 & 0 & 1 & \mathbb{R} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Group homomorphism  $\phi: \mathbb{Z} \rightarrow \mathrm{GL}_d(\mathbb{R})$   
(i.e.,  $\phi(m+n) = \phi(m) \cdot \phi(n)$ )

$\nRightarrow$  extends to homo  $\hat{\phi}: \mathbb{R} \rightarrow \mathrm{GL}_d(\mathbb{R})$ .

(Only allow *continuous* homos.)

*Proof by contradiction.*



Suppose  $\exists$  homo  $\hat{\phi}: \mathbb{R} \rightarrow \mathrm{GL}_d(\mathbb{R})$   
 with  $\hat{\phi}(n) = \phi(n)$  for all  $n \in \mathbb{Z}$ .

$$\hat{\phi}(0) = I \quad \Rightarrow \det(\hat{\phi}(0)) = 1 > 0$$

$\mathbb{R}$  connected

$$\Rightarrow \hat{\phi}(\mathbb{R}) \text{ connected}$$

$$\Rightarrow \det(\hat{\phi}(\mathbb{R})) \text{ connected}$$

$$\Rightarrow \det(\hat{\phi}(\mathbb{R})) > 0$$

$$\Rightarrow \det(\phi(1)) > 0$$

Maybe  $\det(\phi(1)) < 0$ .  $\rightarrow \leftarrow$

(Any  $A \in \mathrm{GL}_d(\mathbb{R})$ , let  $\phi(n) = A^n$ .)

Group homo  $\phi: \mathbb{Z} \rightarrow \mathrm{GL}_d(\mathbb{R})$

(i.e.,  $\phi(m+n) = \phi(m) \cdot \phi(n)$ )

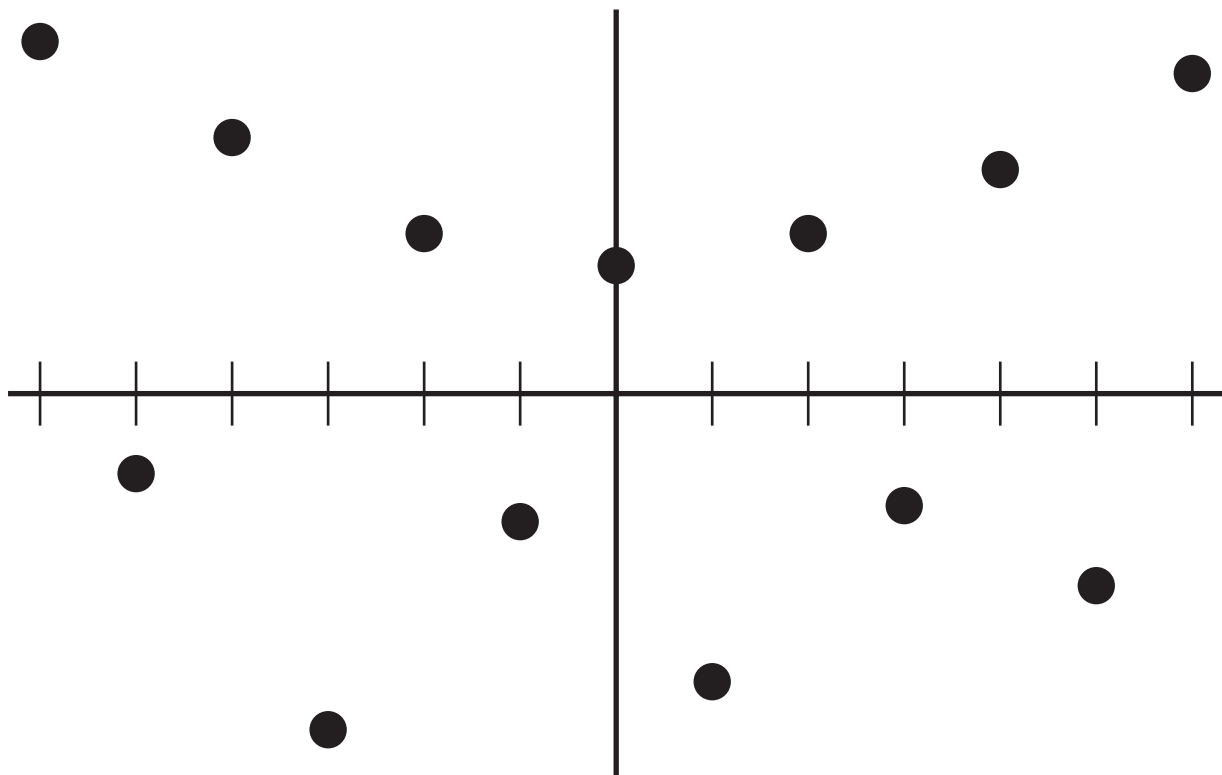
$\nRightarrow$  extends to homo  $\hat{\phi}: \mathbb{R} \rightarrow \mathrm{GL}_d(\mathbb{R})$ .

Because: maybe  $\det(\phi(1)) < 0$ .

However,  $\det(\phi(\text{even})) > 0$ .

$$\begin{aligned} \det(\phi(2m)) &= \det(\phi(m+m)) \\ &= \det(\phi(m) \cdot \phi(m)) \\ &= \left( \det(\phi(m)) \right)^2 \\ &> 0. \end{aligned}$$

May have to ignore odd numbers:  
restrict attention to even numbers.



Analogously, may need to restrict to multiples of 3  
(or 4 or 5 or ...)

Restrict attention to multiples of  $N$

$\{\text{multiples of } N\}$  is a subgroup of  $\mathbb{Z}$

“Restrict attention to a finite-index subgroup”

**Prop.** *Group homomorphism  $\phi: \mathbb{Z}^k \rightarrow \mathrm{GL}_d(\mathbb{R})$   
 $\Rightarrow \phi$  “almost” extends to homo  $\hat{\phi}: \mathbb{R}^k \rightarrow \mathrm{GL}_d(\mathbb{R})$   
 such that  $\hat{\phi}(\mathbb{R}^k) \subset \overline{\phi(\mathbb{Z}^k)}$ . (“Zariski closure”)*

This means  $\mathbb{Z}^k$  is *superrigid* in  $\mathbb{R}^k$ .

“Homomorphisms defined on  $\mathbb{Z}^k$  almost  
 extend to be defined on  $\mathbb{R}^k$ ”

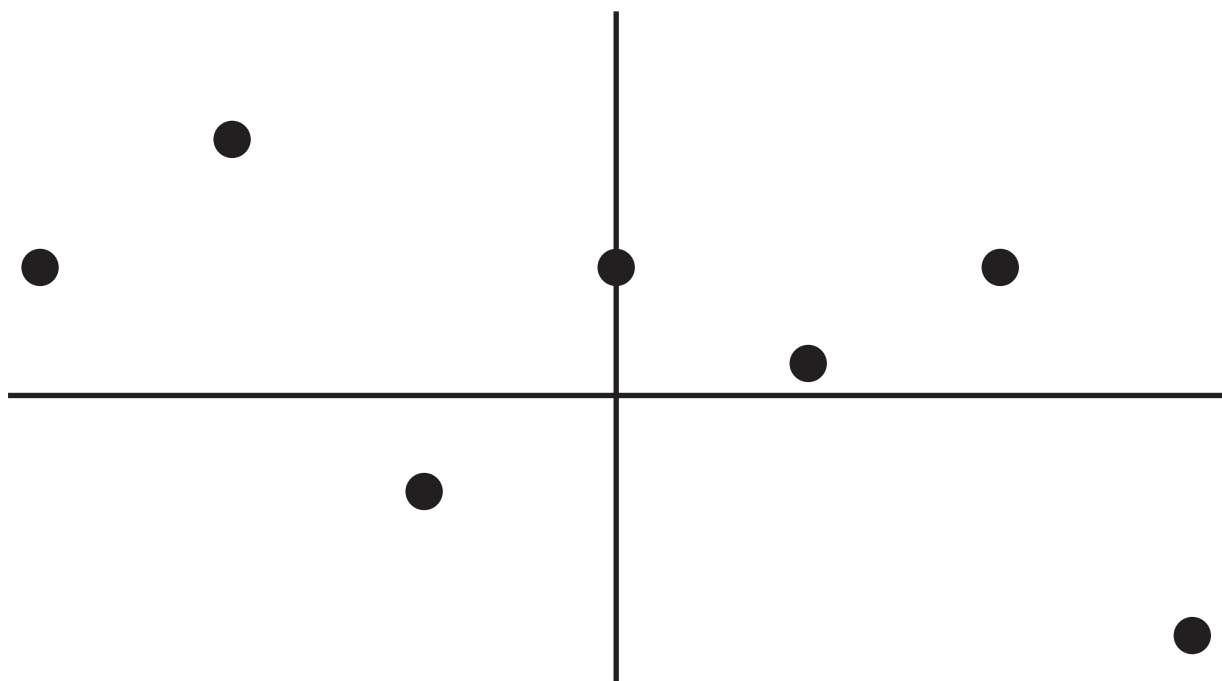
Generalize to nonabelian groups.

Lagrange interpolation:

there is a polynomial curve

$$y = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_0$$

through any  $n + 1$  points.





Idea: Zar closure is like *convex hull*.

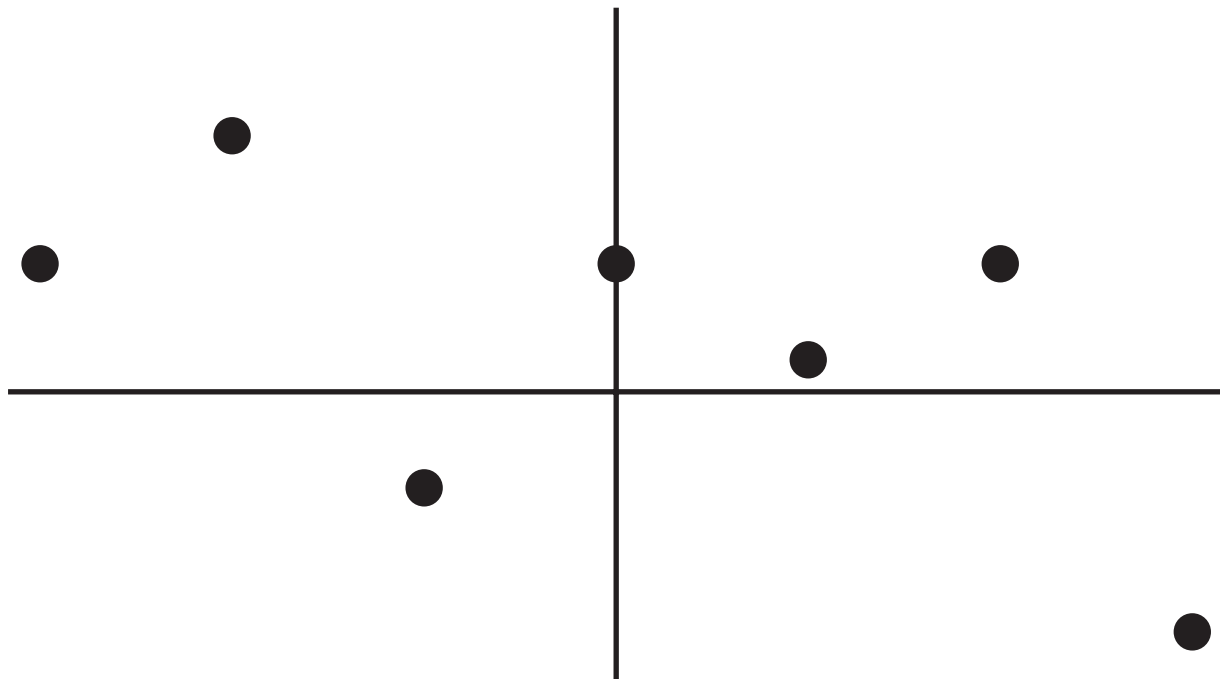


Image of  $\phi$  controls image of  $\hat{\phi}$ .

*Eg.* If all matrices in  $\phi(\mathbb{Z})$  commute, then all matrices in  $\hat{\phi}(\mathbb{R})$  commute.

*Eg.* If all matrices in  $\phi(\mathbb{Z})$  fix a vector  $v$ , then all matrices in  $\hat{\phi}(\mathbb{R})$  fix  $v$ .

### (3. The analogy)

#### **Combinatorial superrigidity:**

Make a copy of the object,  
according to the combinatorial rules.

The copy is the exact same shape as the original.

Maybe not exactly the same object:

- may be rotated from the original position;
- may be translated from original position.

These are trivial modifications:

rotations and translations are symmetries of the whole universe (Euclidean space  $\mathbb{R}^3$ ).

## Combinatorial superrigidity:

Make a copy of the object, according to the combinatorial rules.

The same result can be obtained by keeping the original object and moving the whole universe to a new position.

“If the object can be moved somewhere, then the whole universe can be moved there.”

Let  $H$  be a subgroup of a group  $G$ .

*Superrigid* means:

homomorphism  $\phi: H \rightarrow \mathrm{GL}_d(\mathbb{R})$  extends to homomorphism  $\hat{\phi}: G \rightarrow \mathrm{GL}_d(\mathbb{R})$

## Group-theoretic superrigidity:

Make a copy of  $H$  as a group of matrices.

The same copy of  $H$  can be obtained by moving all of  $G$  into a group of matrices.

## 4. Superrigid subgroups

**Prop.** Group homomorphism  $\phi: \mathbb{Z}^k \rightarrow \mathrm{GL}_d(\mathbb{R})$   
 $\Rightarrow \phi$  “almost” extends to homo  $\hat{\phi}: \mathbb{R}^k \rightarrow \mathrm{GL}_d(\mathbb{R})$   
 such that  $\hat{\phi}(\mathbb{R}^k) \subset \overline{\phi(\mathbb{Z}^k)}$ . (“Zariski closure”)

This means  $\mathbb{Z}^k$  is *superrigid* in  $\mathbb{R}^k$ .

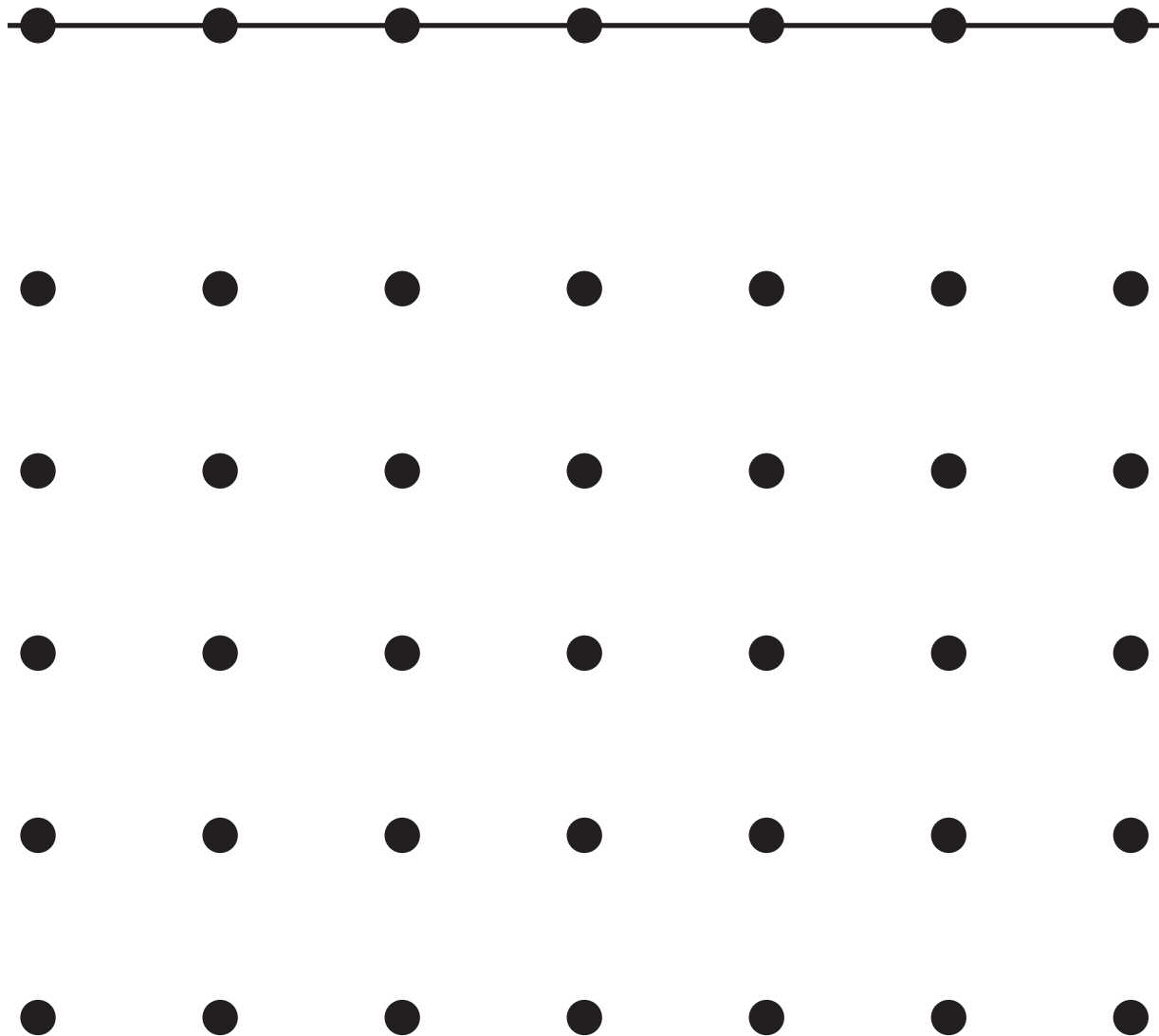
*Generalize to nonabelian groups.*

$\mathbb{Z}^k$  is a *lattice* in  $\mathbb{R}^k$ . I.e.,

- $\mathbb{R}^k$  is a (simply) connected grp  
 (“Lie group”)
- $\mathbb{Z}^k$  is a discrete subgroup
- all of  $\mathbb{R}^k$  is within a bounded distance of  $\mathbb{Z}^k$

$$\exists C, \forall x \in \mathbb{R}^k, \exists m \in \mathbb{Z}^k, \quad d(x, m) < C.$$

$H$  is a *lattice* in  $G$



All of  $\mathbb{R}^k$  is within  $\sqrt{k}/2$  of  $\mathbb{Z}^k$

Let us consider *solvable* groups.

A connected subgroup  $G$  of  $GL_d(\mathbb{C})$  is **solvable** if it is upper triangular

$$G \subset \begin{pmatrix} \mathbb{C}^\times & \mathbb{C} & \mathbb{C} \\ 0 & \mathbb{C}^\times & \mathbb{C} \\ 0 & 0 & \mathbb{C}^\times \end{pmatrix}$$

(or is after a change of basis).

*Eg.* All abelian groups are solvable.

*Proof.* Every matrix can be triangularized over  $\mathbb{C}$ .

Pairwise commuting matrices can be simultaneously triangularized.

**Prop.**  $H$  superrigid in  $G$   
 $\Rightarrow \overline{H} = \overline{G} \pmod{\overline{Z(G)}}.$

*Proof.* The inclusion  $H \hookrightarrow \mathrm{GL}_d(\mathbb{R})$   
 must extend to  $G \hookrightarrow \mathrm{GL}_d(\mathbb{R})$   
 with  $G \subset \overline{H}$ .

Converse:

**Thm** (Witte). *A lattice  $H$  in a solvable grp  $G$  is superrigid iff  $\overline{H} = \overline{G} \pmod{\overline{Z(G)}}.$*

*Examples of lattices.*

$$G = \begin{pmatrix} 1 & \mathbb{R} & \mathbb{R} & \mathbb{R} \\ 0 & 1 & \mathbb{R} & \mathbb{R} \\ 0 & 0 & 1 & \mathbb{R} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$H = \begin{pmatrix} 1 & \mathbb{Z} & \mathbb{Z} & \mathbb{Z} \\ 0 & 1 & \mathbb{Z} & \mathbb{Z} \\ 0 & 0 & 1 & \mathbb{Z} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$G = \begin{pmatrix} \mathbb{R}^+ & 0 & 0 \\ 0 & \mathbb{R}^+ & 0 \\ 0 & 0 & \mathbb{R}^+ \end{pmatrix}$$

$$H = \begin{pmatrix} 2^{\mathbb{Z}} & 0 & 0 \\ 0 & 2^{\mathbb{Z}} & 0 \\ 0 & 0 & 2^{\mathbb{Z}} \end{pmatrix}$$



$$G = \begin{pmatrix} 1 & \mathbb{R} & \mathbb{C} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \overline{G} = G$$

$$H = \begin{pmatrix} 1 & \mathbb{Z} & \mathbb{Z} + \mathbb{Z}i \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \overline{H} = G$$

$$G' = \begin{pmatrix} 1 & t & \mathbb{C} \\ 0 & 1 & 0 \\ 0 & 0 & e^{2\pi it} \end{pmatrix}$$

$$\overline{G'} = \begin{pmatrix} 1 & \mathbb{R} & \mathbb{C} \\ 0 & 1 & 0 \\ 0 & 0 & \mathbb{T} \end{pmatrix}$$

$$H' = \begin{pmatrix} 1 & \mathbb{Z} & \mathbb{Z} + \mathbb{Z}i \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = H$$

$H$  is a lattice in both  $G$  and  $G'$ .

$$\overline{H} = G \neq \overline{G'} \quad \text{so } \overline{H} \neq \overline{G'}$$

$H$  is *not* superrigid in  $G'$ .

E.g., the identity map  $\phi: H \rightarrow H$   
does not extend to homo  $\hat{\phi}: G' \rightarrow \overline{H}$ .

*Proof.* Note that  $\overline{H} = G$  is abelian  
but  $G'$  is not abelian.

A nonabelian group cannot be embedded in an abelian one.

$\overline{H} \neq \overline{G'}$ : some of the rotations associated to  $G'$  do not come from rotations associated to  $H$

$$\text{rot} \begin{pmatrix} \alpha & * \\ 0 & \beta \end{pmatrix} = \begin{pmatrix} \frac{\alpha}{|\alpha|} & 0 \\ 0 & \frac{\beta}{|\beta|} \end{pmatrix}$$

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